

Ramp/Soak Process Controller

E5AK-T/E5EK-T

Advanced Ramp/Soak Process Controllers Ideal for Worldwide Use

- E5AK-T offers up to eight patterns of simple programming control (4 patterns for E5EK-T), with 16 steps per pattern
- Modular structure, one-stock type
- High-accuracy: 100 ms sampling (for analog input)
- Conforms to international EMC and safety standards.
- IP66/NEMA4 (indoor use) front face
- Serial communications (RS-232C, RS-422 and RS-485) and transfer output (4 to 20 mA)
- Position-proportional control model is offered
- Heat/Cool control
- 24 V AC/DC types also available

Ordering Information ____

When ordering, order control output boards and option boards separately. Example: for a relay control output, order the E53-R output board in addition to the standard Process Controller (E5AK-T/E5EK-T). Also specify the current transformer.

PROCESS CONTROLLERS

Item	Description	Part number
Base unit	Standard model with terminal cover	E5AK-TAA2-500 AC100-240
		E5AK-TAA2-500 AC/DC24
	Position-proportional model with terminal cover	E5AK-TPRR2-500 AC100-240
		E5AK-TPRR2-500 AC/DC24
	Standard model with terminal cover	E5EK-TAA2-500 AC100-240
		E5EK-TAA2-500 AC/DC24
	Position-proportional model with terminal cover	E5EK-TPRR2-500 AC100-240
		E5EK-TPRR2-500 AC/DC24

Note: 1. When using the heater burnout alarm function with a standard model, the linear output board cannot be used for the control outputs (heat).

2. The Process Controller provides transfer outputs at 4 to 20 mA for the PV and other values and control outputs at 4 to 20 mA for the current outputs.





OUTPUT BOARDS

Item	Description	Part number
Output board	Relay	E53-R
	SSR	E53-S
	Pulse (NPN) 12 VDC	E53-Q
	Pulse (NPN) 24 VDC	E53-Q3
	Pulse (PNP) 24 VDC	E53-Q4
	Linear (4 to 20 mA)	E53-C3
	Linear (0 to 20 mA)	E53-C3D
	Linear (0 to 10 V)	E53-V34
	Linear (0 to 5 V)	E53-V35

Note: The Controller uses a dedicated, high-resolution output board. The E53-C current output board for the E5 \Box X cannot be used with the E5AK-T/E5EK-T Controller.

OPTION BOARD

Item	Description	Part number	
Option board	Event input	E53-AKB	
	Communication (RS-232C)	E53-AK01	
	Communication (RS-422)	E53-AK02	
	Communication (RS-485)	E53-AK03	
	Transfer output	E53-AKF	

Note: 1. The option board can be used either by the E5AK or E5EK.

2. The E5AK-T allows a maximum of three option boards to be mounted. Refer to the *Operations* Section for mounting combinations. The E5EK-T allows only one option board to be mounted.

ACCESSORIES (ORDER SEPARATELY)

Current Transformer

Item	Hole diameter	Part number
Current transformer (See Note.)	5.8 mm	E54-CT1
	12.0 mm	E54-CT3

Note: No CT is required unless the heater burnout alarm function is used.

Terminal Cover

Item	Connectable models	Part number
Terminal cover	E5AK	E53-COV0809
	E5EK	E53-COV08

Unit Label

Item	Part number
Unit label	Y92S-L1

TEMPERATURE RANGES

Platinum Resistance Thermometer

Input (See Note.)	JPt100	Pt100
Range	-199.9° to 650.0°	-199.9° to 650.0°
	-199.9° to 999.9°	-199.9° to 999.9°
Setting (°C/°F) (main setting and alarm)	0	1

Note: Switch selectable.

Thermocouple

Input (see note)		K1	K2	J1	J2	Т	E	L1	L2	U	N	R	S	В	W	PLII
Range	°C	-200 to 1,300	0.0 to 500.0	-100 to 850	0.0 to 400.0	-199.9 to 400.0	0 to 600	-100 to 850	0.0 to 400.0	-199.9 to 400.0	-200 to 1,300	0 to 1,700	0 to 1,700	100 to 1,800	0 to 2,300	0 to 1,300
	°F	-300 to 2,300	0.0 to 900.0	-100 to 1,500	0.0 to 750.0	-199.9 to 700.0	0 to 1,100	-100 to 1,500	0.0 to 750.0	-199.9 to 700.0	-300 to 2,300	0 to 3,000	0 to 3,000	300 to 3,200	0 to 4,100	0 to 2,300
Resolution (°C/°F) (main settin and alarm)	ng	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16

Note: Switch selectable: Setting number is factory-set to 2 (K1).

Thermocouple W is W/Re5-26 (tungsten rhenium 5, tungsten rhenium 26).

Current/Voltage

Input (See Note.)	Current input		Voltage input			
	4 to 20 mA	0 to 20 mA	1 to 5 V	0 to 5 V	0 to 10 V	
Range	One of following ranges depending on re -1999 to 9999 -199.9 to 999.9 -19.99 to 99.99 -19.99 to 99.99 -19.99 to 9.999		ing on results of scaling			
Setting	17	18	19	20	21	

Note: Switch selectable.

Specifications _____

RATINGS

Model		E5EK/AK-T (Standard)	E5EK/AK-T (24 V Type)			
Supply voltage		100 to 240 VAC, 50/60 Hz	24 VAC/VDC, 50/60 Hz			
Power consumption	E5AK-T	16 VA	12 VA, 8 W			
	E5EK-T	15 VA				
Operating voltage range		85% to 110% of rated supply voltage	ge			
Input	Thermocouple	K, J, T, E, L, U, N, R, S, B, W, PLII				
	Platinum resistance thermometer	JPt100, Pt100				
	Current input	4 to 20 mA, 0 to 20 mA (Input impe	edance: 150 Ω)			
	Voltage input	1 to 5 V, 0 to 5 V, 0 to 10 V (Input in	mpedance: 1 MΩ)			
Control output	Standard model	According to Output Unit (see Output	out Board Ratings and Characteristics)			
	Position-proportional model (See Note.)	2 Relay outputs: SPST-NO, 1 A at	250 VAC (including inrush current)			
Auxiliary output		SPST-NO, 3 A at 250 VAC (resistive load)				
Control method		ON/OFF or advanced PID control (with auto-tuning)				
Setting method		Digital setting using front panel keys or communications features				
Indication method		7-segment digital display and LEDs				
Potentiometer		100 Ω to 2.5 k Ω				
Event input	Contact input	ON: 1 kΩ max., OFF: 100 kΩ min.				
	No-contact input	ON: residual voltage: 1.5 V max., OFF: leakage current: 0.1 mA max.				
Transmission output		4 to 20 mA, permissible load impedance: 600Ω max., resolution: approx. 2,600 steps				
Current transformer input	ıt	Connect only Omron Current Transformer (E54-CT1 or E54-CT3)				
Additional functions	Standard	Manual output, heating/cooling control, SP limiter, loop burnout alarm, MV limiter, MV change rate limiter, input digital filter, input shift, run/reset, protect functions, scaling function				
Approved standards		UL 1092, CSA22.2 No. 14, CSA22.2 No. 1010-1 Conforms to EN50081-2, EN50082-2, EN61010-1 (IEC1010-1) Conforms to VDE0106/part 100 (Finger Protection), when the separately- ordered terminal cover is mounted.				

Note: All control outputs are insulated from the input circuit.

■ CHARACTERISTICS

Indication accuracy	Thermocouple	(±0.3% of indication value or $\pm 1^{\circ}$ C, whichever greater) ± 1 digit max.				
(See Note 1.)	Platinum resistance thermometer	(±0.2% of indication value or ±0.8°C, whichever greater) ±1 digit max.				
	Analog input	±0.2% (of indication value) ±1 digit max.				
Hysteresis	·	0.01% to 99.99% FS (in units of 0.01% FS)				
Proportional band (P)		0.1% to 999.9% FS (in units of 0.1% FS)				
Integral (reset) time (I)		0 to 3,999 s (in units of 1 s)				
Derivative (rate) time (D)		0 to 3,999 s (in units of 1 s)				
Control period		1 to 99 s (in units of 1 s)				
Manual reset value		0.0% to 100.0% (in units of 0.1%)				
Alarm setting range		-1,999 to 9,999 or -199.9 or 999.9 (decimal point position dependent on input type or result of scaling)				
Set time		0 to 99 hrs 59 min or 0 to 99 min 59 s				
Program capacity		8 patterns (E5AK-T) or 4 patterns (E5EK-T), 16 steps				
Programming method		Time or ramp setting method				
Time accuracy		±0.2% (±500 ms) of the set value				
Sampling period Temperature input		250 ms				
(See Note 2.)	Analog input	100 ms				
Insulation resistance		20 MΩ min. (at 500 VDC)				
Dielectric strength		2,000 VAC, 50/60 Hz for 1 min between terminals of different polarities				
Vibration resistance		Malfunction: 10 to 55 Hz, 10 m/s ² (approx. 1G) for 10 min each in X, and Z directions				
		Destruction: 10 to 55 Hz, 20 m/s ² (approx. 2G) for 2 hrs each in X, Y, an Z directions				
Shock resistance		Malfunction: 200 m/s ² min. (approx. 20G), 3 times each in 6 directions (100 m/s ² (approx. 10G) applied to the relay)				
		Destruction: 300 m/s ² min. (approx. 30G), 3 times each in 6 directions				
Ambient temperature	Operating	-10°C to 55°C (14°F to 131°F) with no icing and 3-year warranty period: -10°C to 50°C (14°F 122°F)				
	Storage	-25°C to 65°C (-13°F to 149°F) with no icing				
Ambient humidity	Operating	35% to 85%				
Enclosure ratings	Front panel	NEMA4 for indoor use (equivalent to IP66)				
	Rear case	IEC standard IP20				
Terminals		IEC standard IP00				
Memory protection		Non-volatile memory (number of writings: 100,000 operations)				
Weight	E5AK-T	approx. 450 g				
	E5EK-T	approx. 320 g				
	Mounting bracket	approx. 65 g				

(This table continues on the next page.)

Note: 1. The indication accuracy of the K1, T, and N thermocouples at a temperature of -100°C max. is ±2°C ±1 digit maximum. The indication accuracy of the U and L thermocouples at any temperature is ±2°C ±1 digit maximum. The indication accuracy of the B thermocouple at a temperature of 400°C max. is unrestricted. The indication accuracy of the R and S thermocouples at a temperature of 200°C max. is ±3°C ±1 digit maximum. The indication accuracy of the W thermocouples at any temperature is (±0.3% of the indicated value or ±3°C, whichever is greater) ±1 digit maximum. The indication accuracy of the PLII thermocouple at any temperature is (±0.3% of the indicated value or ±2°C, whichever is greater) ±1 digit maximum.

2. The sampling period of the standard model with CT and remote SP inputs is 250 ms.

Characteristics Table - continued from previous page

EMC	Emission Enclosure: Emission AC Mains: Immunity ESD: Immunity RF-interference: Immunity Conducted Disturbance:	EN55011 Group 1 class A EN55011 Group 1 class A EN61000-4-2: 4 kV contact discharge (level 2) 8 kV air discharge (level 3) ENV50140: 10 V/m (amplitude modulated, 80 MHz to 1 GHz) (level 3) 10 V/m (pulse modulated, 900 MHz) ENV50141:10 V (0.15 to 80 MHz)
	Immunity Burst:	(level 3) EN61000-4-4: 2 kV power-line (level 3) 2 kV I/O signal-line (level 4)
Approved standards	UL1092, CSA22.2 No. 14, CSA22 Conforms to EN50081-2, EN50082 Conforms to VDE0106/part 100 (F dered terminal cover is mounted.	

OPTION BOARD RATINGS AND CHARACTERISTICS

Model	Description		Specifications	
E53-AKB	3-AKB Event input		Contact input: ON: 1 k Ω max., OFF: 100 k Ω min.	
			No-contact input: ON: residual voltage 1.5 V max., OFF: leakage current 0.1 mA max.	
E53-AK01	Communications	RS-232C	Transmission method: Half-duplex	
E53-AK02		RS-422	Synchronization method: Start-stop synchronization (asynchronous method) Baud rate: 1.2/2.4/4.8/9.6/19.2 kbps	
E53-AK03		RS-485	- Daud Hale. 1.2/2.4/4.0/3.0/13.2 Kbp3	
E53-AKF	Transfer output		4 to 20 mA: Permissible load impedance: 600 Ω max.; Resolution: approx. 2,600 steps	

Note: Event input is used for switching the target value, run or stop command, or automatic and manual mode with an external signal input.

CURRENT TRANSFORMER RATINGS

Maximum continuous heater current		50 amps
Dielectric strength		1,000 VAC (for 1 min)
Vibration resistance		50 Hz, 98 m/s ² (10G)
Weight	E54-CT1	approx. 11.5 g
	E54-CT3	approx. 50 g
Accessories (E54-CT3 only) Armature		2
	Plug	2

HEATER BURNOUT ALARM

Max. heater current	Single-phase 50 A VAC (See Note 1.)
Heater current value display accuracy	±5% FS±1 digit max.
Heater burnout alarm setting range	0.1 to 49.9 A (in units of 0.1 A) (See Note 2.)
Min. detection ON time	190 ms (See Note 3.)

Note: 1. Use the K2CU-F \square A- \square GS (with gate input terminals) for the detection of three-phase heater burnout.

2. The heater burnout alarm is always OFF if the alarm is set to 0.0 A and always ON if the alarm is set to 50.0 A.

3. No heater burnout detection or heater current value measurement is possible if the control output (heat) is ON for less than 190 ms.

Nomenclature

E5AK-T

the falling step. Bar Graph

OUT1

ON.

ON.

SUB1

ON. SUB2

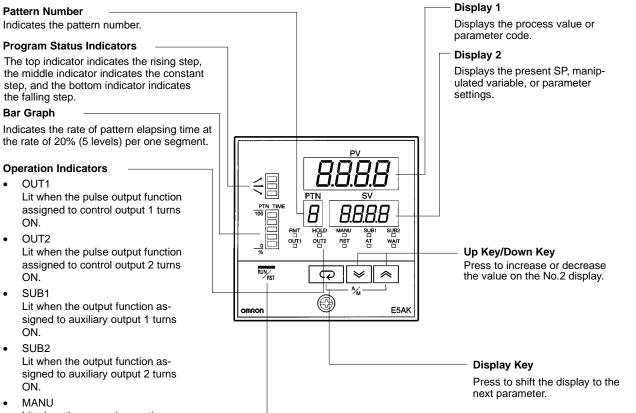
ON.

OUT2

•

.

.



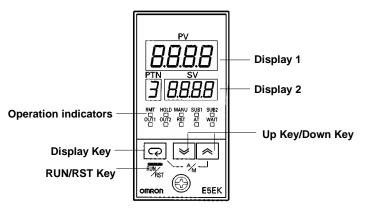
- MANU Lit when the manual operation mode.
- RST Lit when the operation is reset. RMT
- Lit during remote operation.
- AT

Flashes during auto-tuning.

- HOLD
- Lit when the program is on hold. WAIT

Lit when the program is waiting.

E5EK-T



RUN/RST Key

Switches between RUN and RESET mode.

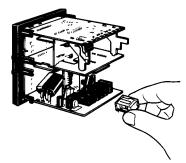
Operation

Note: Before changing any switch settings, always turn OFF the power supply to the Process Controller

SETTINGS

- 1. On a standard model, set up the output boards for control outputs 1 and 2 before mounting the Controller.
- 2. On a position-proportional model, the relay output board is already set, so this setup operation is unnecessary. (Do not replace with other output boards.)
- 3. When setting up the output boards, remove the internal mechanism from the housing and insert the output boards into the sockets for control outputs 1 and 2.

Setting Up the Output Board



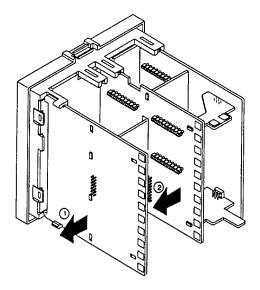
Removing the Output Board

To replace the output board, use a flat-blade screwdriver to push up the output board.

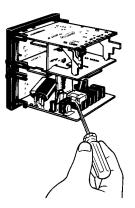
Setting Up the Option Board

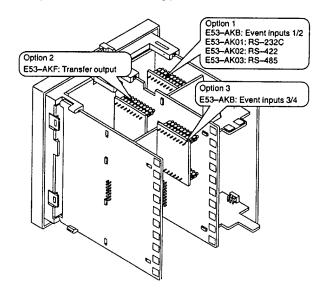
E5AK-T

1. Remove the power board and option boards in the order shown in the following diagram.



2. Insert the option boards into the sockets for options 1 to 3. The following diagram shows the relationship between the option boards and mounting positions.

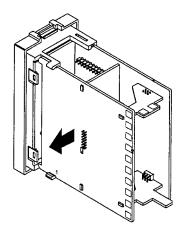




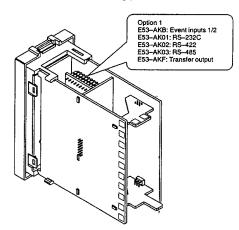
3. Mount the option boards and the power board in the order shown.

E5EK-T

1. Remove the power board and option boards in the order shown in the following diagram.



2. Insert the option board into the socket for option 1. The following diagram shows the relationship between the option board and mounting position.

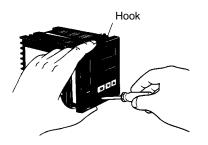


3. Mount the option board and the power board in the order shown.

Removing the Internal Mechanism

To remove the internal mechanism from the housing, use a Phillips screwdriver matching the screw on the lower part of the front panel.

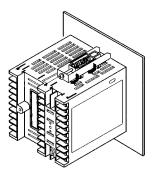
1. Turn the screw counterclockwise while pressing the hook on the upper part of the front panel.



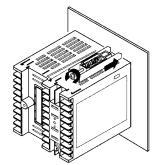
2. Carefully pull out the internal mechanism while holding the left and right sides of the front panel.

Mounting

- 1. Insert the E5AK-T Controller into the panel's mounting hole at the position shown in the figure below.
- 2. Fit the mounting bracket (accessory) into the fixing slots on the top and bottom of the rear case.



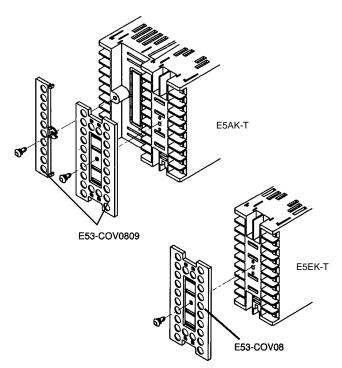
3. Tighten the mounting bracket screws on the upper and lower parts of the E5AK-T in small increments alternately and equally until the ratchet starts to slide.



E53-COV0809, E53-COV08 Terminal Cover (Order Separately)

Fasten the terminals covers as follows by using the snap pins.

Note: Snap pins are provided with the terminal covers.

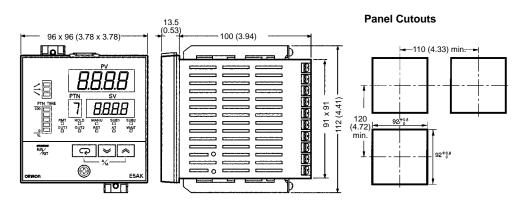


Dimensions

Unit: mm (inch)

E5AK-T



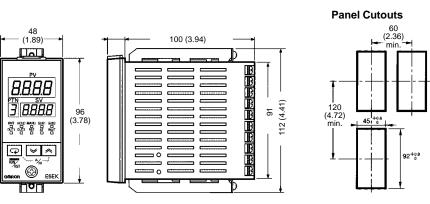


Note: 1. Recommended panel thickness is 1 to 8 mm.

2. Maintain the specified vertical and horizontal mounting space between each Unit. Units must not be closely mounted (vertically or horizontally).

E5EK-T





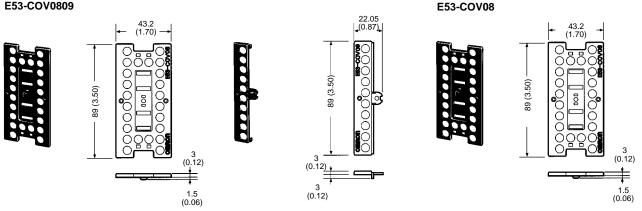
Note: 1. Recommended panel thickness is 1 to 8 mm.

2. Maintain the specified vertical and horizontal mounting space between each Unit. Units must not be closely mounted vertically or horizontally.

■ ACCESSORIES (ORDER SEPARATELY)

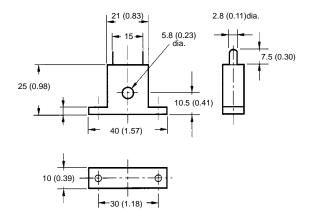
Terminal Cover

E53-COV0809



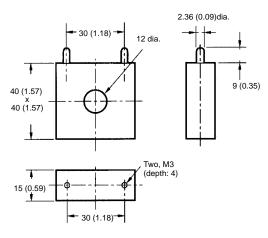
Current Transformer E54-CT1





Unit: mm (inch) E54-CT3

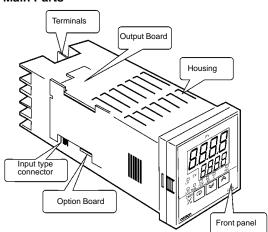




Installation

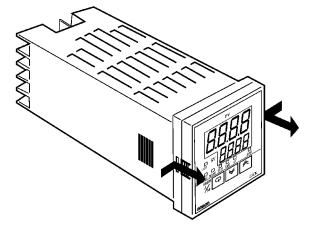
INSTALLATION

Main Parts



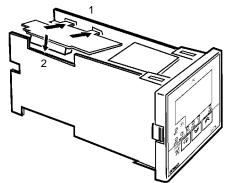
Removing Internal Mechanism

While pressing the hooks on the left and right sides of the front panel, carefully pull the internal mechanism from the housing. (Refer to the drawing below.)



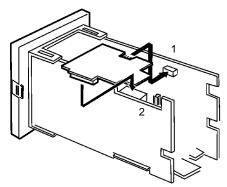
SETTING UP THE OUTPUT BOARD

- 1. Two rectangular holes are provided on the power board (right side of Controller). Fit the two protrusions of the output board into these two holes.
- 2. With the output board fitted into the power board, fit the output board into the connector on the control board (left side of Controller).



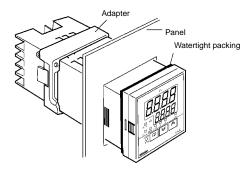
SETTING UP THE OPTION BOARD

- 1. Place the Controller bottom up, and fit the option board horizontally into the connector on the power board (right side of Controller).
- 2. With the power board connected, fit the board vertically into the connector on the control board (left side of controller).



MOUNTING THE CONTROLLER

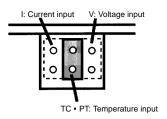
- 1. Insert the Controller into the panel's mounting hole at the position shown in the figure below.
- 2. Push the adapter along the Controller body from the terminals up to the panel, and fasten temporarily.
- 3. Tighten the two fixing screws on the adapter. When tightening screws, tighten the two screws alternately keeping the torque to approximately 0.29 to 0.39 N m, or 3 to 4 kgf cm.



Input Jumper Setting

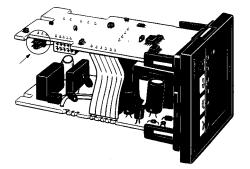
Note: The jumper is factory-set to TC • PT (temperature input).

Set the jumper to temperature, voltage, or current input according to the sensor connected to the input terminal.



Note: Do not touch the pins of the jumper connector when setting the input type.

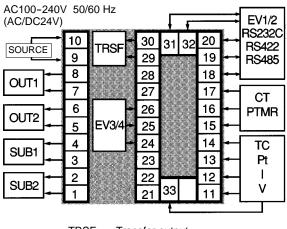
After setting the jumper, put on the housing, pressing the housing until the hooks of the front panel snap on.



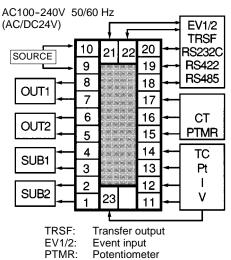
WIRING TERMINALS

Terminal Arrangement

E5AK-T



TRSF: Transfer output EV1 to 4: Event input PTMR: Potentiometer E5EK-T



■ WIRING PRECAUTIONS

- Use ducts to separate input leads and power lines in order to protect the Controller and its lines from external noise.
- Solderless terminals are recommended when wiring the Controller.
- Tighten the terminal screws using a torque no greater than 0.78 N m, or 8 kgf cm max. Be careful not to tighten the terminal screws too tightly.

Power Blocks for E5AK-T/EK-T

The E5AK/E5EK has independent power supplies for each of the terminal blocks shown below.

E5AK-T

A 		В			(2
	10		30	31 32	20	
لسسما	9	1	29 28		19	
	8	1	28		18	
в	7	l	27	. 1	17	
	6	1	26	8	16	
8I	5	С	25		15	
	4]	24		14	
E	3		23		13	
	2	I	22		12	
	1		21	33	11	
E					D	-

E5EK-T

A	۱	B	/C	(С
	10	21	22	20	
l	9			19	
	8		IJ	18	
В	7			17	
	6		X10000	16	
	5 4		00000	15	
	4		00000	14	
E	3			13	
	2			12	
	1	23		11	
F					D

E5AK-T WIRING

In the following wiring diagrams, the left side of the terminal numbers indicate the inside of the Controller.

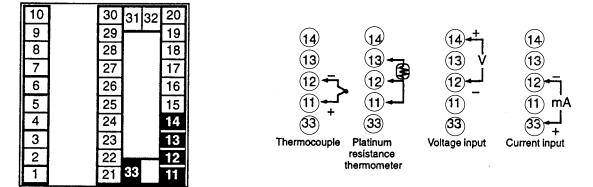
Power Supply

Input 100 to 240 VAC or AC/DC 24 V to terminal numbers 9 and 10 according to the specifications.

10		31 32	20
9	29		19
8	28		18
7	27		17
6	26		16
5	25		15
4	24		14
3	23		13
2	22		12
1	21	33	11

Sensor Input

Connect the sensor input to terminal numbers 11 to 14 and 33 as follows according to the input type.



Control Output

Terminal numbers 7 and 8 are for control output 1 (OUT1), and terminal numbers 5 and 6 are for control output 2 (OUT2). The following diagrams show the available output boards and their internal equalizing circuits.

10 9 8 7 6 5 4	30 31 32 20 29 19 19 28 18 17 26 16 15 25 15 14	86 75 Relay	₹		^{+v} 86 ⁺ GND -75 PNP
3	23 13	E53-R	E53-S	E53-Q	E53-Q4
2	22 12 21 33 11	┌ <u>──⑧ⓒ╸⁺</u> ┐ ┉ѧ [ւ]	┌─®©┵┐	E53-Q3	
		ڷ <u>؈۞</u>	ليوي ال		
		4 to 20mA/0 to 20mA	0 to 10V/0 to 5V	_	
		E53-C3 E53-C3D	E53-V34 E53-V35		

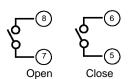
With E53-V u output boards, approx. 2 V is output for one second after the power is interrupted.

Specifications for Each Output Board

Model	Output type	Specifications
E53-R	Relay	5 A at 250 VAC
E53-S	SSR	1 A at 75 to 250 VAC
E53-Q E53-Q3 E53-Q4	Voltage (NPN) Voltage (NPN) Voltage (PNP)	NPN: 40 mA at 12 VDC (with short-circuit protection) NPN: 20 mA at 24 VDC (with short-circuit protection) PNP: 20 mA at 24 VDC (with short-circuit protection)
E53-C3 E53-C3D	4 to 20 mA 0 to 20 mA	4 to 20 mA; permissible load impedance: 600 Ω max.; resolution: approx. 2600 0 to 20 mA; permissible load impedance: 600 Ω max.; resolution: approx. 2600
E53-V34 E53-V35	0 to 10 V 0 to 5 V	0 to 10 VDC; permissible load impedance: 1 k Ω min.; resolution: approx. 2600 0 to 5 VDC; permissible load impedance: 1 k Ω min.; resolution: approx. 2600

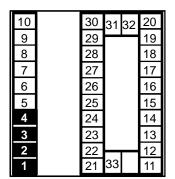
With E5AK-PRR2 Controllers, the relay output (1 A at 250 VAC) is fixed.

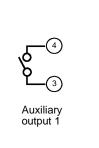
When replacing the output board, use the E53-R. The following diagrams show the relationship between terminals and open/close relay settings.



Auxiliary Output

Terminal numbers 3 and 4 are for auxiliary output 1 (SUB1) and terminal numbers 1 and 2 are for auxiliary output 2 (SUB2). The following diagrams show the internal equalizing circuits for the auxiliary outputs:





Output specifications are as follows: SPST-NO, 3 A at 250 VAC

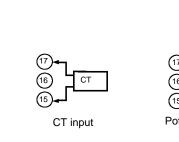
CT Input/Potentiometer

When using the HBA function on the E5AK-TAA2 Controller, connect CT input (CT) to terminal numbers 15 to 17. When monitoring the valve opening on the E5AK-TPRR2 Controller, connect the potentiometer (PTMR) to terminal numbers 15 to 17. Connect each of these inputs as follows:

Auxiliary

output 2

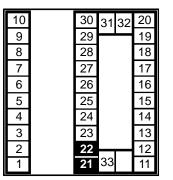
10	30	31	32	20
9	29			19
8	28			18
7	27			17
6	26			16
5	25			15
4	24			14
3	23			13
2	22			12
1	21	33		11



For details on CT inputs, refer to *Appendix, About Current Transformer* in the *E5AK-T/E5EK-T User's Manual (H83/H85)*. For details on the potentiometer, refer to the *Instruction Manual* for the valve connected to the Controller. The variable resistance range is 100 Ω to 2.5 k Ω .

Remote SP Input

Connect the input (RSP) to be used as the remote SP to terminal numbers 21 and 22. Only 4 to 20 mA inputs can be connected. Connect the input as follows:

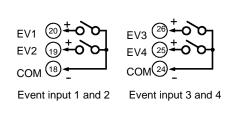




Event Input

Connect event inputs 1 and 2 (EV1/2) to terminal numbers 18 to 20, and events 3 and 4 (EV3/4) to terminal numbers 24 to 26. However, note that terminal numbers 18 to 20 cannot be used on Controllers with a communications function. Connect the event inputs as follows:

10	30	31 32	20
9	29		19
8	29 28		18
7	27		17
6	26 25 24		16
5	25		15
4	24		14
3	23		13
2	22		12
1	21	33	11

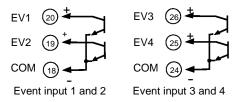


Terminals 18 and 24 (COM) are connected internally.

Use event inputs under the following conditions:

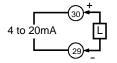
Contact input	ON: 1 kΩ max. OFF: 100 kΩ min.
No-contact input	ON: Residual voltage 1.5 V max., OFF: Leakage current 0.1 mA max.

Polarities during no-contact input are as follows:



Transfer Output

Connect transfer output (TRSF) to terminal numbers 29 and 30. The internal equalizing circuit for transfer output is as follows:



Transfer output specifications are as follows: 4 to 20 mA Permissible load impedance: 600 Ω max. Resolution: approx. 2600

Communications

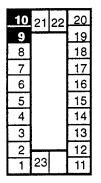
Terminal numbers 18 to 20, 31 and 32 can be used only on Controllers with communications boards (E53-AK01/02/03). For details on wiring, refer to *Chapter 6, Using the Communications Function* in the *E5AK-T/E5EK-T User Manuals (H83 and H85)*.

E5EK-T WIRING

In the following wiring diagrams, the left side of the terminal numbers indicate the inside of the Controller.

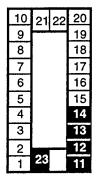
Power Supply

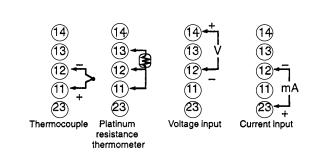
Input 100 to 240 VAC or AC/DC 24 V to terminal numbers 9 and 10 according to the specifications.



Sensor Input

Connect the sensor input to terminal numbers 11 to 14 and 33 as follows according to the input type.

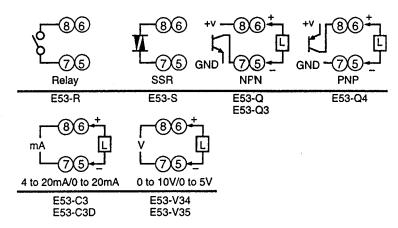




Control Output

Terminal numbers 7 and 8 are for control output 1 (OUT1), and terminal numbers 5 and 6 are for control output 2 (OUT2). The following diagrams show the available output boards and their internal equalizing circuits.

			_
10	21	22	20
9			19
8			18
7	[17
6	[16
5			15
4			14
4 3			13
2			12
1	23		11



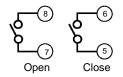
With E53-V O output boards, approx. 2 V is output for one second after the power is interrupted.

Specifications for Each Output Board

Model	Output type	Specifications
E53-R	Relay	5 A at 250 VAC
E53-S	SSR	1 A at 75 to 250 VAC
E53-Q E53-Q3 E53-Q4	Voltage (NPN) Voltage (NPN) Voltage (PNP)	NPN: 40 mA at 12 VDC (with short-circuit protection) NPN: 20 mA at 24 VDC (with short-circuit protection) PNP: 20 mA at 24 VDC (with short-circuit protection)
E53-C3 E53-C3D	4 to 20 mA 0 to 20 mA	4 to 20 mA, permissible load impedance: 600 Ω max., resolution: approx. 2600 0 to 20 mA, permissible load impedance: 600 Ω max., resolution: approx. 2600
E53-V34 E53-V35	0 to 10 V 0 to 5 V	0 to 10 VDC, permissible load impedance:1 k Ω min., resolution: approx. 2600 0 to 5 VDC, permissible load impedance: 1 k Ω min., resolution: approx. 2600

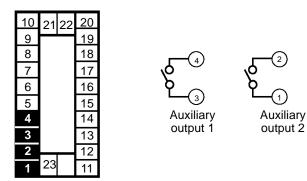
With E5EK-TPRR2 Controllers, the relay output (1 A at 250 VAC) is fixed.

When replacing the output board, use the E53-R. The following diagrams show the relationship between terminals and open/close relay settings.



Auxiliary Output

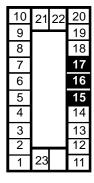
Terminal numbers 3 and 4 are for auxiliary output 1 (SUB1) and terminal numbers 1 and 2 are for auxiliary output 2 (SUB2). The following diagrams show the internal equalizing circuits for the auxiliary outputs:

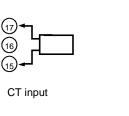


Output specifications are as follows: SPST-NO, 3A at 250 VAC

CT Input/Potentiometer

When using the HBA function on the E5EK-TAA2 Controller, connect CT input (CT) to terminal numbers 15 to 17. When monitoring the valve opening on the E5EK-TPRR2 Controller, connect the potentiometer (PTMR) to terminal numbers 15 to 17. Connect each of these inputs as follows:





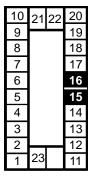
Potentiometer

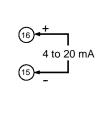
For details on CT inputs, refer to Appendix, About Current Transformer in the E5AK-T/E5EK-T User's Manual (H83/H85).

For details on the potentiometer, refer to the *Instruction Manual* for the valve connected to the Controller. The variable resistance range is 100 Ω to 2.5 k Ω .

Remote SP Input

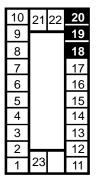
Connect the input (RSP) to be used as the remote SP to terminal numbers 15 and 16. However, note that the remote SP cannot be used on the E5EK-TPRR2 Controller. Only 4 to 20 mA inputs can be connected. Connect the input as follows:

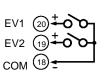




Event Input

Connect event inputs 1 and 2 (EV1/2) to terminal numbers 18 to 20. However, note that terminal numbers 18 to 20 cannot be used on Controllers with a communications function. Connect the event inputs as follows:



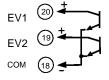


Event input 1 and 2

Use event inputs under the following conditions:

Contact input	ON: 1 k Ω max., OFF: 100 k Ω min.
	ON: Residual voltage 1.5 V max., OFF: Leakage current 0.1 mA max.

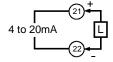
Polarities during no-contact input are as follows:



Event input 1 and 2

Transfer Output

Connect transfer output (TRSF) to terminal numbers 21 and 22. The internal equalizing circuit for transfer output is as follows:



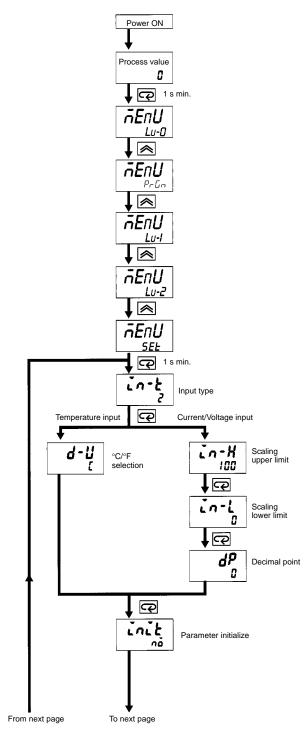
Transfer output specifications are as follows:4 to 20 mA, Permissible load impedance: 600 Ω max., Resolution: Approx. 2600

Communications

Terminal numbers 18 to 22 can be used only on controllers with communications boards (E53-AK01/02/03). For details on wiring, refer to *Chapter 6, Using the Communications Function* in the *E5AK-T/E5EK-T User Manuals (H088-E3-1 and H089-E3-1)*.

AFTER TURNING POWER ON

Determine the I/O specifications of the Process Controller in setup mode.



INPUT TYPE

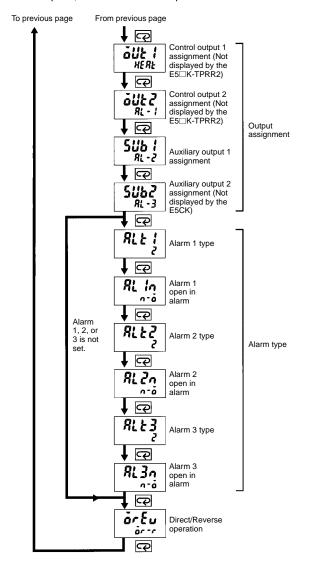
Set the code according to the following table. Default is "2: K1 thermocouple."

Platinum Resistance Thermometer

Set value	Input typ	e		
0	JPt100	-199.9 to 650.0 (°C) /-199.9 to 999.9 (°F)	Platinum resistance	
1	Pt100	-199.9 to 650.0 (°C) /-199.9 to 999.9 (°F)	thermometer	
2	K1	-200 to 1,300 (°C) /-300 to 2,300 (°F)	Thermocouple	
3	K2	0.0 to 500.0 (°C) /0.0 to 900.0 (°F)		
4	J1	-100 to 850 (°C) /-100 to 1,500 (°F)		
5	J2	0.0 to 400.0 (°C) /0.0 to 750.0 (°F)		
6	Т	-199.9 to 400.0 (°C) /-199.9 to 700.0 (°F)		
7	E	0 to 600 (°C) /0 to 1,100 (°F)		
8	L1	−100 to 850 (°C) /-100 to 1,500 (°F)		
9	L2	0.0 to 400.0 (°C) /0.0 to 750.0 (°F)		
10	U	-199.9 to 400.0 (°C) /-199.9 to 700.0 (°F)		
11	N	-200 to 1,300 (°C) /-300 to 2,300 (°F)		
12	R	0 to 1,700 (°C) /0 to 3,000 (°F)		
13	S	0 to 1,700 (°C) /0 to 3,000 (°F)		
14	В	100 to 1,800 (°C) /300 to 3,200 (°F)		
15	W	0 to 2,300 (°C) /0 to 4,100 (°F)		
16	PLII	0 to 1,300 (°C) /0 to 2,300 (°F)		
17	4 to 20 r	mA	Current input	
18	0 to 20 r	nA		
19	1 to 5 V		Voltage input	
20	0 to 5 V			
21	0 to 10 \	/	1	

PARAMETER INITIALIZE

Parameter initialization sets all parameters to default values except for the input type, scaling upper limit, scaling lower limit, decimal point, and $^{\circ}CI^{\circ}F$ selection parameters.



OUTPUT ASSIGNMENTS

Signals available as allocated outputs are the control output (heat), control output (cool), alarm 1, alarm 2, alarm 3, LBA, and HBA. The auxiliary outputs of the Process Controller cannot be used as control outputs.

Control output (heat), control output (cool), alarm 1, alarm 2, alarm 3, LBA, error 1 (input error), and error 2 (A/D converter error) output functions are available. These functions are assigned to control outputs 1 and 2 and auxiliary outputs 1 and 2.

The assignment destination of each output function is restricted. Refer to the tables provided under the headings, *Standard Models and Position-Proportionate Models*.

STANDARD MODELS

Assignment destination	Contro output)l	Auxilia output	iry
Output function	1	2	1	2
Control output (heat)	Yes	Yes		
Control output (cool)	Yes	Yes		
Alarm 1	Yes	Yes	Yes	Yes
Alarm 2	Yes	Yes	Yes	Yes
Alarm 3	Yes	Yes	Yes	Yes
НВА	Yes	Yes	Yes	Yes
LBA	Yes	Yes	Yes	Yes
Error 1: Input error			Yes	Yes
Error 2: A/D converter error			Yes	Yes

With control output (cool), the conditions for switching from standard control to heating and cooling control are reached when the output function is assigned at the cooling side during heating and cooling control.

In other words, heating and cooling control is carried out when control output (cool) is assigned, and standard control is carried out when output is not assigned.

POSITION-PROPORTIONAL MODELS

Assignment destination	Control output		Auxiliary output	
Output function	1	2	1	2
Alarm 1			Yes	Yes
Alarm 2			Yes	Yes
Alarm 3			Yes	Yes
Error 1: Input error			Yes	Yes
Error 2: A/D converter error			Yes	Yes
Error 3: RSP input error			Yes	Yes

LBA

The LBA (loop break alarm) function is available when it is assigned as an output. The LBA function is not available when a memory or A/D converter error results.

LBA is a function for determining that an error has occurred somewhere on the control loop and outputting an alarm when the process value does not change with the manipulated variable at a maximum or minimum state. Accordingly, the LBA function can be used as a means for detecting a malfunctioning control loop.

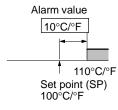
ALARM MODE SELECTORS

Alarm outputs are available if they are allocated as outputs. Factory setting is "2: Upper-limit alarm (deviation)."

Switch	Alarm operation	Alarm output	
setting		When X is positive	When X is negative
1	Upper- and lower-limit alarm (deviation)	ON OFF SP	Always ON
2	Upper-limit alarm (deviation)	ON OFFSP	ON + X + OFF SP
3	Lower-limit alarm (deviation)	ON OFF SP	ON + X + OFF SP
4	Upper- and lower-limit range alarm (deviation)	ON OFF SP	Always OFF
5	Upper- and lower-limit alarm with standby se- quence (deviation)	OFF SP	Always OFF
6	Upper-limit alarm with standby sequence (deviation)	ON OFFSP	ON OFF SP
7	Lower-limit alarm with standby sequence (deviation)	ON OFF SP	ON OFF SP
8	Absolute-value upper-limit alarm	ON X	ON X OFF 0
9	Absolute-value lower-limit alarm	ON X OFF 0	
10	Absolute-value upper-limit alarm with standby sequence	ON OFF 0	ON X OFF 0
11	Absolute-value lower-limit alarm with standby sequence		

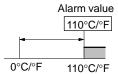
Deviation Alarm

If the alarm mode selector is set to a number between 1 and 7, alarm values are set to the width deviated from the set point as shown in the following illustration.



Absolute Alarm

If the alarm mode selector is set to 8 or 9, alarm values are set to the absolute value based on $0^\circ C/^\circ F$ as shown in the following illustration.



CLOSE IN ALARM/OPEN IN ALARM

When the Controller is set to "close in alarm," the status of the alarm output function is output as it is. When set to "open in alarm," the status of the alarm output function is output inverted.

Condition	Alarm	Output	Output LED
Close in alarm	ON	ON	Lit
	OFF	OFF	Not lit
Open in alarm	ON	OFF	Lit
	OFF	ON	Not lit

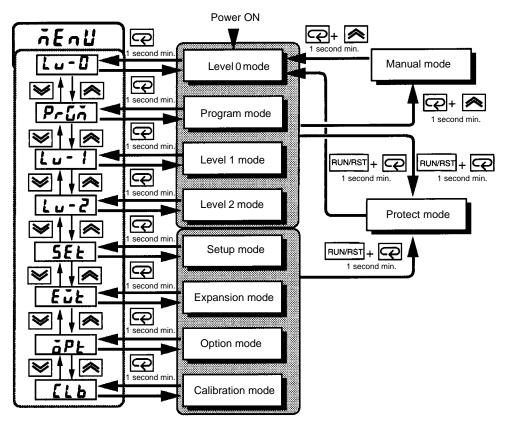
Alarm type and close in alarm (normally open)/open in alarm (normally close) can be set independently from each alarm.

Close in alarm/Open in alarm is set in the "alarm 1 to 3 open in alarm" parameters (setup mode). Factory setting is "close in alarm" [$a - \bar{a}$].

PARAMETER OPERATION LIST

Switching to modes other than manual or protect mode is carried out using the mode selection in the menu display.

The figure below shows all parameters in the order that they are displayed. Some parameters are not displayed depending on the protect mode setting and conditions of use.



PARAMETERS AND MENUS

For more details on the functions of each part and display contents, refer to the *E5AK-T/E5EK-T User Manuals*. All functions selected with the Controller in setup or expansion mode or all optional functions of the Process Controller may not be displayed.

Protect Mode

The protect function is for preventing unwanted modification of parameters and switching between run and reset operation or auto and manual operation.

Manual Mode

In this mode, the Controller can be switched to manual operation. The manipulated variable can be manipulated manually only in this mode.

Level 0 Mode

Set the Controller to this mode during normal operation. In this mode, you can change the set point and pattern during operation, and execute step operation (e.g. advance). You can only monitor (not change) the process value, step No., standby time, pattern elapsing time, pattern execution count, and manipulated variable.

Program Mode

This is the programming mode. In this mode, you can set the number of steps used in each pattern, pattern execution count, alarm values, set points for each step, step time, and time signals for two steps.

Level 1 Mode

This is the main mode for adjusting control. In this mode, you can execute AT (auto-tuning), set up the control period, PID parameters, heater burnout alarm (HDA) conditions, and set alarm values.

Level 2 Mode

This is the auxiliary mode for adjusting control. In this mode, you can set the parameters for limiting the manipulated variable, switch between the remote and local modes, and set the loop break alarm (LBA), alarm hysteresis, and the digital filter value of inputs.

Setup Mode

This is the mode for setting the basic specifications. In this mode, you can set parameters that must be checked or set before an operation such as the input type, scaling, output assignments, and direct/reverse operation.

Expansion Mode

This is the mode for setting expanded functions. In this mode, you can set SP setting limiter, switching between advanced PID control or ON/OFF control, program time unit, selection of step time/rate of rise, time unit of ramp rise rate, and the time for automatic return to the monitoring display.

Option Mode

This is the mode for setting optional functions. You can select this mode only when an option board is mounted in the Controller. In this mode, you can set the communications conditions, transfer output and event input parameters to match the type of option board mounted in the Controller. Heater burnout alarm function and position-proportional travel time are also found in this mode.

Calibration Mode

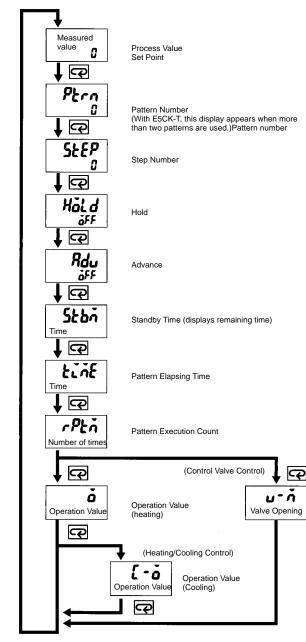
This mode is provided so that the user can calibrate inputs and output. When calibrating input, the selected input type is calibrated. Whereas, transfer output can be calibrated only when the communications board (E53-AKF) is set in the Controller.

PARAMETER OPERATION

Refer to the *E5AK-T* and *E5EK-T* User Manuals (H83 and H85) for each parameter and the calibration mode in detail.

Also refer to "Settings" in the Operation Section.

Level 0 Mode



PV/SP

The process value is displayed on the No.1 display and the set point is displayed on the No.2 display.

When the multi-SP function is in use, the value of whichever is set, set point 0 or 1, is linked.

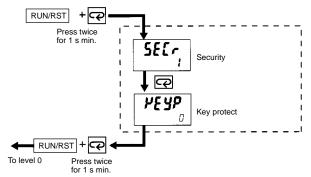
Remote SP Monitor

Monitors remote SP in the local SP mode.

Set Point During SP Ramp

Monitors the set point when the SP ramp function is used.

PROTECT MODE



Security

Any mode marked with "X" in the following table is not displayed on the menu when this parameter is set to "0" to "3."

Mode	Set value				
	0	1	2	3	4
Calibration		х	х	х	х
Option			х	х	х
Expansion			х	х	х
Setup			х	х	х
Level 2				х	х
Level 1, 0					х

The Unit will be in only level 0 mode and the menu will not be available when this parameter is set to "4" to "6."

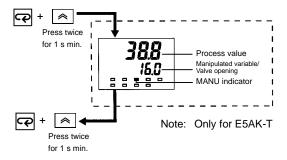
Only the "PV/SP" parameter in the level 0 mode can be used when this parameter is set to "5."

Only the "PV/SP" parameter in the level 0 mode can be used when this parameter is set to "6."

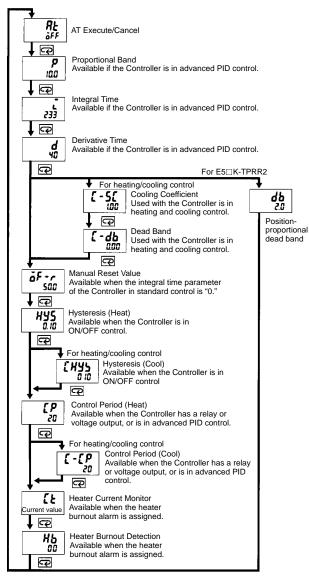
Key Protect

Invalidate the automatic, manual, run, and reset functions.

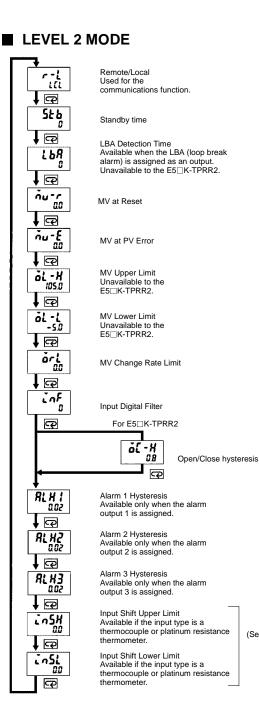
MANUAL MODE



LEVEL 1 MODE



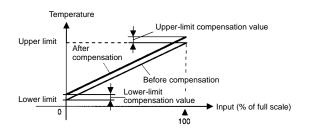
(See Input Shift)



Input Shift

When temperature input is selected, scaling is not required. This is because input is treated as the "temperature" as it is matched to the input type. However, note that the upper- and lower-limit values of the sensor can be shifted. For example, if both the upper- and lower-limit values are shifted by 1.2°C, the process value (before shift) is regarded as 201.2°C after shift when input is 200°C before shift.

To set the input shift, set shift values in the "input shift upper limit" and "input shift lower limit" parameters (level 2 mode).



EXPANSION MODE 5L-X Target Value 1300 Upper Limit • 🖸 51-1 Target Value Lower Limit 200 **P** [ntl PID/ON/OFF Pčd (not displayed for control valve control) **↓** 🖸 P-in At Power ON [ān - 🖸 ESEE At Operation End r St **P** P-no Number of Patterns (displayed for E5CK-T) ↓ 🖸 £-11 Program Time Unit HHAA -R E-Pr Time setting/Inclination Setting FILLE - Q Prü Inclination Setting Time Unit (used for setting inclination) ñ - Q PuSt PV Start (used for setting time) SP 9 Weight Width (available for E5AK-T or E5EK-T) 0 1 🖓 r PRL Alarm Valid During Ramping ٥n ↓ @ rlinR Run-all Valid (with E5CK-T, this display appears ŏFF when more than two patterns are used.) - -RLFR Available if the Controller is in advanced PID control. 065 ↓ œ AT Calculated Gain Available if the Controller is in advanced PID control. 1.0 ↓ œ **۲٤۲** Automatic Display Reset Time AT Hysteresis RE-H

Available if the Controller is in advanced PID control with the ST set to OFF.

LBA Detection Width Available only when the LBA (loop break alarm) function is assigned. Unavailable to the E5⊡K-TPRR2.

0.2

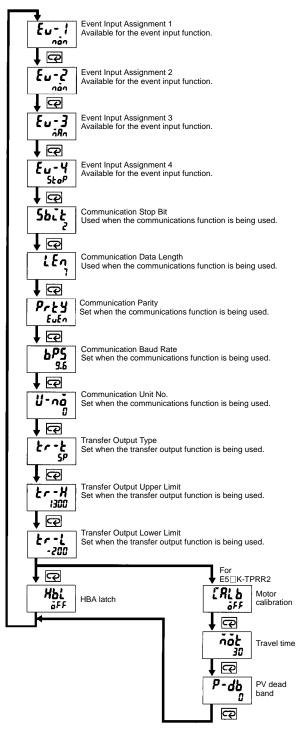
0.2

- Q

<u> 1989</u>

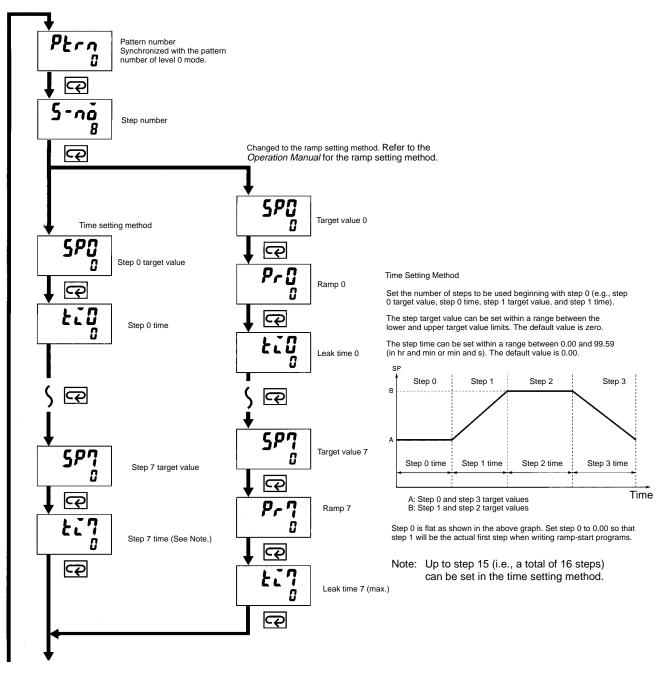
P

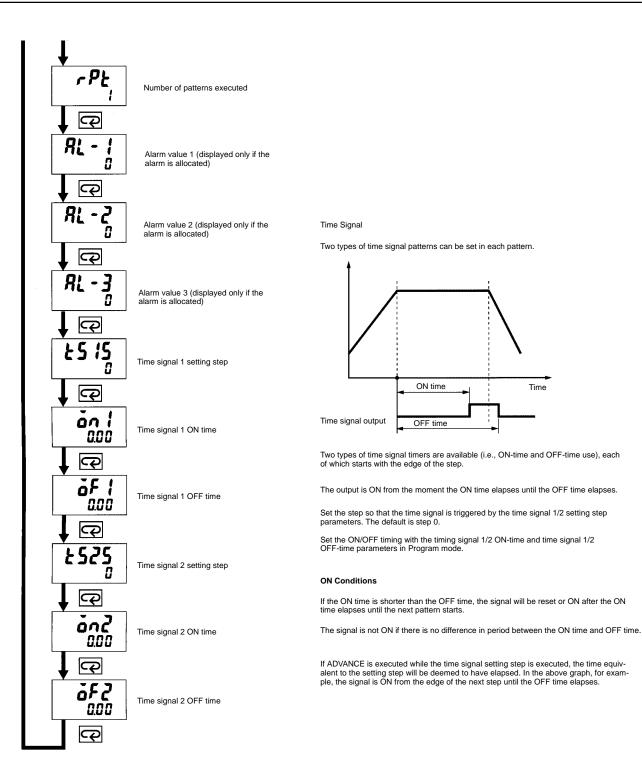
OPTION MODE



OMRON

PROGRAM MODE





HOW TO USE THE ERROR DISPLAY

When an error has occurred, the No.1 display alternately indicates error codes together with the current display item. This section describes how to check error codes on the display, and the actions that must be taken to remedy the problem.

<u>5.8 r r</u>	Input Error
Meaning	Input is in error.
Action	Check the wiring of inputs, disconnections, and shorts, and check the input type and the input type jumper connector.
Operation at Error	For control output functions, output the manipulated variable matched to the setting of the "MV at PV error" parameter (level 2 mode). Alarm output functions are activated when the upper limit is exceeded.
	Memory Error
Meaning	Internal memory operation is in error
Action	First, turn the power OFF then back ON again. If the display remains the same, the $E5 \square K$ -T Controller must be repaired. If the display is restored to normal, the probable cause may be external noise affecting the control system. Check for external noise.
Operation at Error	Control output functions turn OFF (2 mA max. at 4 to 20 mA output, and output equivalent to 0% in case of other outputs). Alarm output functions turn OFF.
[[3]3]	A/D Converter Error
Meaning	Internal circuits are in error.
Action	First, turn the power OFF then back ON again. If the display remains the same, the $E5 \square K$ -T Controller must be repaired. If the display is restored to normal, the probable cause may be external noise affecting the control system. Check for external noise.
Operation at Error	Control output functions turn OFF (2 mA max. at 4 to 20 mA output, and output equivalent to 0% in case of other outputs). Alarm output functions turn OFF.
<i><u>Я.</u>Е г г</i>	Calibration Data Error

This error is output only during temperature input and is displayed for two seconds when the power is turned ON.

Meaning	Calibration data is in error.
Action	Must repair.
Operation at Error	Both control output functions and alarm output functions are active. However, note that the readout accuracy is not assured.

CCCC Display JJJJ	y Range Over			
Meaning	Though not an error, this is displayed when the process value exceeds the display range when the control range (setting range $\pm 10\%$) is larger than the display range (-1999 to 9999).			
	When less than "-1999" CCCC			
	 When greater than "9999" 			
Operation	Control continues, allowing normal operation.			
Meaning	Motor calibration has ended with an error.			
Meaning	Motor calibration has ended with an error			
Action	First, correctly connect the wiring for the potentiometer, open output, and close output.			
	Execute the motor calibration again.			
Operation Procedure				

Operation at Error

When motor calibration is executed, open output will operate and then close output will operate. However, as the value is incorrect, the result turns out to be an error.

Precautions

OPERATING ENVIRONMENT

- Operate the Controller within the rated ambient operating temperature, ambient operating humidity, and storage temperature ranges.
- Use the Controller according to the vibration resistance, shock resistance, and enclosure ratings.
- Do not install the Controller in places with corrosive gas or excessive dust.
- Do not install the Controller near machines generating highfrequency noise.

- The dimensions of the Controller conform to DIN 43700.
- Recommended panel thickness is 1 to 8 mm.
- Mount the Unit horizontally.

CONNECTION

- To reduce inductive noise influence, the lead wires connecting the input type to the Controller must be separated from the power lines and load lines.
- Use the specified compensating conductors for thermocouples. Use lead wires having a small resistance for platinum resistance thermometers.

CONNECTION EXAMPLE

- Wire the terminals of the Unit using solderless terminals.
- The tightening torque applied to the terminal screws of the Unit must be approximately 0.78 N m or 8 kgf cm.
- Use the following type of solderless terminals for M3.5 screws.





OPERATION

- The alarm outputs of a model with an alarm function may not turn ON correctly when the model malfunctions. The use of alarm equipment with the Controller is recommended.
- The parameters and internal switch are set before shipping so that the Unit will function normally. Change the settings of the parameters and internal switch according to the application if necessary.
- After power has been supplied to the Controller, several seconds are required until the relay is turned ON. Consider this time delay when designing sequenced circuits which incorporate a Controller.
- Do not use excessive force when removing the internal mechanism from the housing. Protect the internal connector or electronic parts of the Unit from shock.
- Protect against static discharge when changing the settings of the internal switch. Changing the settings on a grounded conductive mat is recommended.
- When connecting the control output board to the Temperature Controller or Process Controller, make sure that the control output board is the appropriate type, or the system may malfunction.
- The heater burnout alarm will not be available if the linear output board is used.

SSR

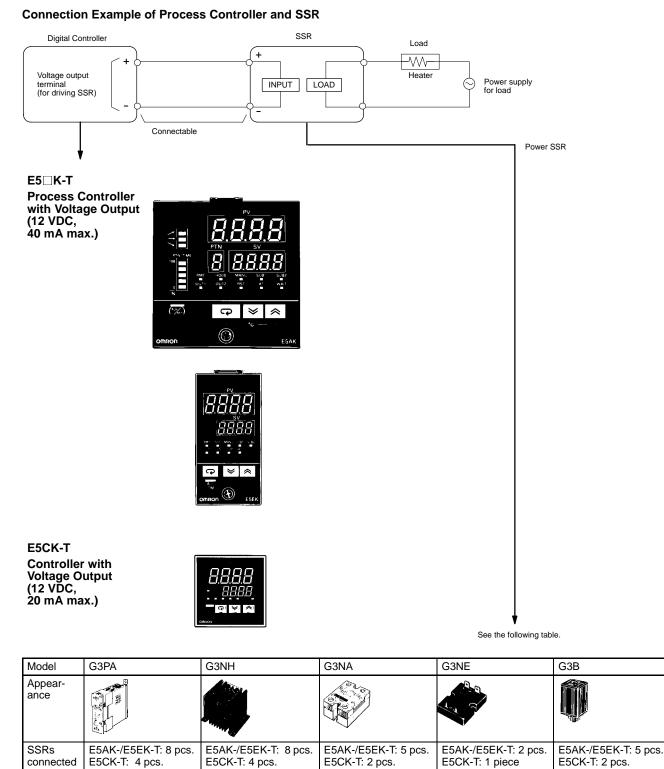
in parallel Rated

input voltage Features 5 to 24 VDC

sink

Thin, monoblock

construction with heat



5 to 24 VDC

For high-power

heater control

5 to 24 VDC

Standard model with

screw terminals

12 VDC

terminals

Compact, low-cost

model with tab

5 to 24 VDC

capacity

Socket, model with 5-A switching

