# High-precision Visual Displacement Measurement System

**Z300** 

2-Dimensional CCD is Built in. A New Type of Displacement Sensor Utilizing the Best and Most Up-to-date Image Processing Technologies.



### **Features**

## Stable measurement of a transparent object or a glass. A wide variety of sensor heads for enhanced detection possibilities.

OMRON's Z300 makes the notion that displacement sensors cannot perform stable measurement of a transparent object or a glass a thing of the past. The newly-developed 2-dimensional CCD (S-CCD) incorporated in the Z300, combined with upgraded performance of the controller, provides enhanced stability and accuracy in measurement of a transparent object. The latest algorithm employed by the Z300 enables optimal sensitivity even if there is a big difference between the amount

of reflected light from the surface and that from the bottom of a glass. Enhanced measurement area and a variety of high-resolution, long-distance sensor heads greatly expand the range of applications.

The Z300 is just another example of OMRON's ongoing challenge to the limits of sensing possibilities.

Z300-S60 Super Long-range Model Detection distance of 600 ± 350 mm

Z300-S10 Long-range Model Detection distance of 100 ± 20 mm

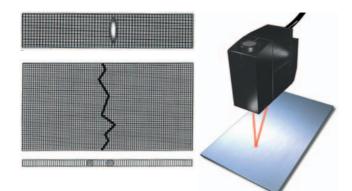
Z300-S5T High-precision Model Detection distance of 50 ± 5 mm

Z300-S2T Super-precision Model Detection distance of 20 ± 1 mm

## The innovative 2-dimensional CCD (S-CCD) is the key to the sensing stability.

# The 2-dimensional CCD also enables high-speed measurement.

A conventional displacement sensor using a 1-dimensional CCD cannot deal with flutter influence to the output. Therefore, the sensor requires increased number of measurements for signal averaging, which leads to slow response time. The S-CCD with a 2-dimensional CCD has solved this disadvantage, by splitting the measurement point into 60 lines for measurement in finer detail. The value per each pixel is then averaged to produce a reliable output, free from flutter interference caused by the object's surface condition. Stable detection and high-speed processing is thus possible with the Z300.

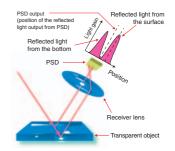


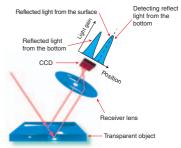
#### CCD makes a difference in measurement of a transparent object.

#### PSD sensor

A PSD sensor using diffuse reflection is virtually prevented from performing measurement due to insufficient reflection distribution from the surface. A sensor using the mirror reflection method, on the other hand, receives reflective light from the bottom or background of the object, which causes an error in determining the target position, impeding accurate measurement. CCD sensor

A CCD using the mirror reflection method is a solution. It can extract only the light reflected off the surface of the target. Accurate measurement of a transparent object is possible without being affected by reflected light from the bottom or background of the object.





## Monitoring as the object is being measured. Measurement data can be recorded and played back.

Easy-to-see color display is another great feature of the Z300 (when connected to a color monitor). Monitoring at each key stage including test and adjustment, operation, or maintenance greatly facilitates efficient, error-free measurement.

## Digital monitor



The measured value is displayed. The use of two colors: green for "Pass" judgement, and red for "High/Low," enhances visual recognition of the measurement result.

## Real-time monitoring



Displays the position of measurement point as well as intensity of the reflected light. Conveniently checks whether optimum measurement is taking place.

Monitoring during recording and playback

#### iking place. rot

# Trend monitor



Continuous measurement values during a certain period of time are shown in chronological order. Changes in the measured values of a moving or rotating object can be checked at a glance.

#### Test mode



Any desired number of measurement data can be stored for testing with a workpiece.

# Conditions during Test mode can be recorded and played back



Test measurement data obtained off-line can be saved for reference for actual in-line measurement.

NG (High/Low) judgement status is recorded and played back.

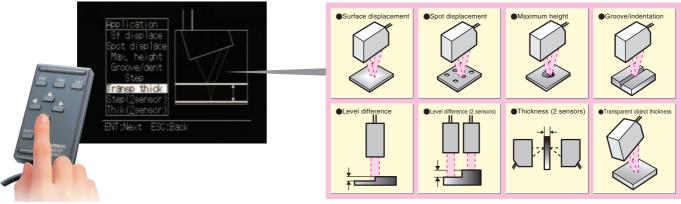


Up to 20 in-line NG data (information including reflected light condition and measurement data) can be recorded for workpiece analysis as well as for troubleshooting.

## Interactive menus provide a variety of measurement functions.

#### Application menu

Settings for measurement methods are easily performed using the menu. Just follow the guidance of the monitor screen.



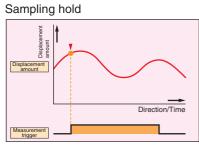
#### Expert menu

Expert menu is available for more advanced measurement. Detailed setting conditions can be conveniently programmed using the menu.

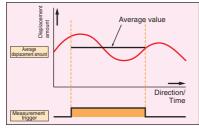
## Enhanced hold functions widen the scope of application.

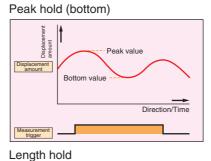
With discrete hold functions equipped within the controller, the Z300 provides a variety of trigger (measurement timing) functions, making otherwise difficult applications a reality — with ease.

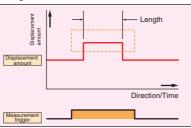
#### Hold functions



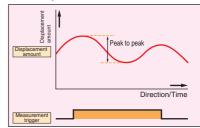
#### Average hold



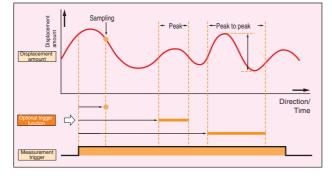




#### Peak to peak hold



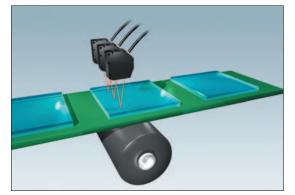
Selectable trigger function



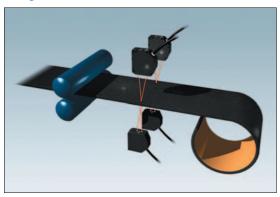
Measurement trigger can be set to the controller for desired measurement timing.

## **Application**

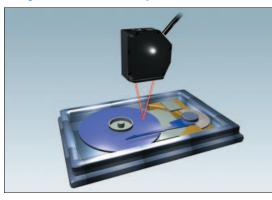
Measuring the thickness of transparent film



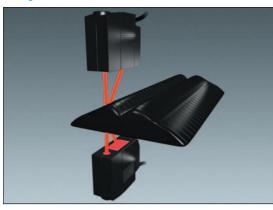
Measuring the thickness of sheet



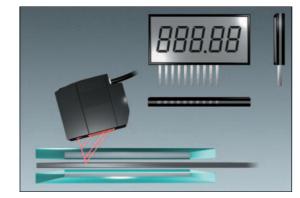
Inspecting the surface uniformity of a hard disk



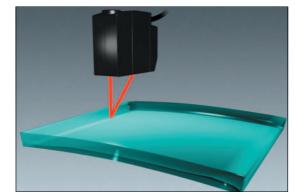
Measuring tire or black rubber thickness



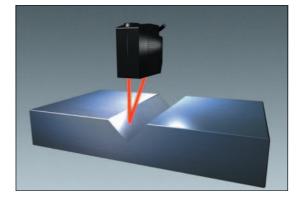
Measurement of electrode position in the display module



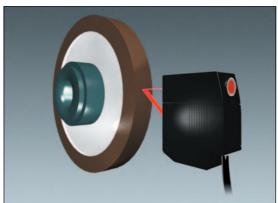
Measurement of warping in transparent plastic



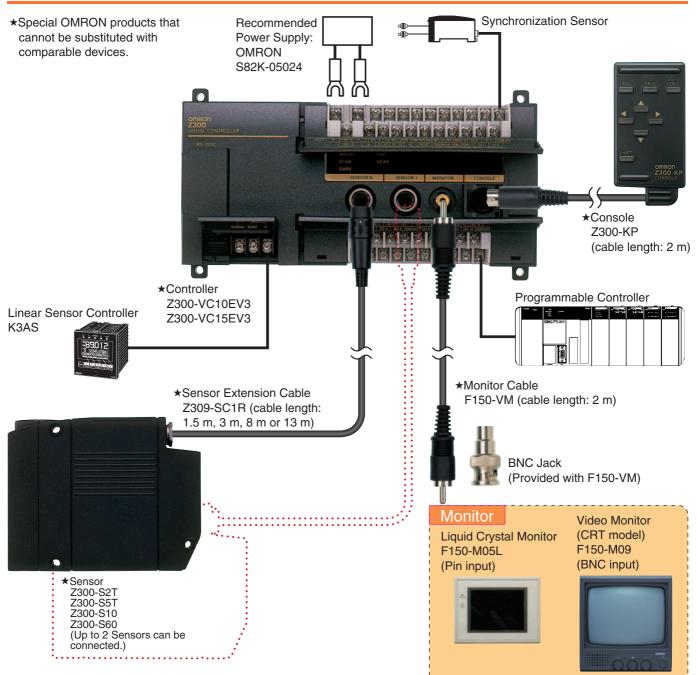
Shape measurement for welding robot control



Grinding measurement of a whetstone



# **System configuration**



# **Ordering Information**

Name Item	Model	Remarks		
	Z300-S2T			
Sensor	Z300-S5T			
Sensor	Z300-S10			
	Z300-S60			
Controller	Z300-VC10EV3	NPN input/output		
Controller	<b>Z300-VC15EV3</b> (See note 1)	PNP input/output		
Console	Z300-KP			
Liquid Crystal Monitor	F150-M05L			
Video Monitor	F150-M09			
Sensor Extension Cable	<b>Z309-SC1R</b> (See note 2)	Cable length: 1.5 m, 3 m, 6 m, 8 m or 13 m		
Monitor Cable	F150-VM			

Notes: 1. Z300-VC15EV3 will be released soon.

2. Specify the required cable length when ordering.

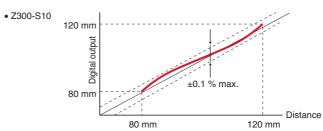
# Rating/performance

### Sensor: Z300-S2T/Z300-S5T/Z300-S10/Z300-S60

	or: Z300-S21/Z300 Model		Z300-S2T Z300-S5T		Z300-S10		Z300-S60	
		Mirror reflection	Diffuse reflection	Mirror reflection	Diffuse reflection	Mirror reflection	Diffuse reflection	Diffuse reflection only
N	leasurement mode							
	ance to surement center	20 mm (with beam cover attached: 16 mm)	±5.2 mm	±44 mm	±50 mm	±94 mm	±100 mm	±600 mm
Mea	surement range	±1 mm		±4 mm	±5 mm	±16 mm	±20 mm	±350 mm (F.S.700 mm)
Light source		Visible-light semiconductor (Wavelength: 1 mW max., C	650 nm, Iass 2)	Visible-light semiconductor laser (Wavelength: 670 nm, 1 mW may				Visible-light semiconductor laser (Wavelength: 658 nm, 15 mW max., Class 3B)
Beam dimensions (See note 1.)		20 µm × 300 µm (distance to mea * Measuremen	surement center)	30 $\mu m \times$ 400 $\mu m$ TYP. (distance to measurement center)		60 $\mu$ m $\times$ 1000 $\mu$ m TYP. (distance to measurement center)		0.3 mm × 16 (10.3*) mm (at 500 mm) * Measurement region
Linearity		±0.05 %F.S. (See note 3.)	±0.05 %F.S. (See note 2.)	±0.1 %F.S. (See note 4.)			±0.07 %F.S. (250 to 750 mm) ±0.1 %F.S. (750 to 950 mm) (See note 4.)	
Resolution      0.4 μm (See notes 5 and 6.)		and 6.)	0.4 μm (See notes 7 and 9.)		1 μm (See notes 7 and 8.)		8 μm (at 350 mm) 40 μm (at 600 mm) (See notes 7 and 8.)	
Sampling period (See note 10.) 540 µs		I			1			
Lights if the workpiese is close to the manufurgement center or is on the								
LED indicators	FAR indicator	Lights if the workpiece is close to the measurement center or is on the far side of the measurement center and inside the measurement region. Flashes if the workpiece is outside the measurement region or if the density is excessive or insufficient.						
Temperature charac- teristic (See note 11.) ±0.01 %F.S./°C								
Degree of protection		IEC IP64		IEC IP67			IEC IP66	
esistar	Ambient operating illumination	Illumination at light-receiving surface: 3,000 lx max., incandescent light						
Environment resistance	Ambient temperature	Operating: 0 to +50 °C, Storage: -15 to +60 °C (with no icing or condensation)						
<i>i</i> iron	Ambient humidity	Operating and storage: 35 % to 85 % (with no condensation)						
Env	Vibration resistance	10 to 150 Hz (double amplitude: 0.35 mm) for 8 min. each in X, Y, and Z directions						
Materials Unit: Die-cast aluminum; Cable Connector: Zinc alloy and bras		ole sheathing: Heat-resistant chlorinated vinyl						
	e length	2 m						50 cm
Minii radiu	mum bending Is	68 mm						
Weight		Approx. 350 g		Approx. 600 g				Approx. 550 g

Notes: 1. Defined at 1/e<sup>2</sup> (13.5 %) of the density at the light center. Light may, however, be present outside this range and if the reflection factor of the light around the

- workpiece is high compared to the workpiece, measurement may be affected. 2. Error with respect to the theoretical line representing the displacement output for measurement of OMRON standard SUS blocks. The linearity varies with the type of workpiece.
- 3. Error with respect to the theoretical line representing the displacement output for measurement of OMRON standard quartz glass. The linearity varies with the type of workpiece.
- 4. Error with respect to the theoretical line representing the displacement output for measurement of OMRON standard white alumina ceramics. The linearity varies with the type of workpiece.



- 5. Displacement conversion value for peak-to-peak of displacement output. These figures are for measurement of OMRON standard quartz glass (mirror reflection mode) or OMRON standard SUS blocks (diffuse reflection) at the measurement center.
- In magnetic fields, it may not be possible to maintain resolution performance characteristics.
- These figures are for when the Sensor is connected to the Z300-VC10EV3, the average number of measurements is 256, and M command RS-232C output is used.
  Displacement conversion value for peak-to-peak of displacement output (for measurement of OMRON standard white alumina ceramic at the measurement
- center). In strong magnetic fields, it may not be possible to maintain resolution performance characteristics.
- 8. With the Z300-VC10EV3, at an average number of measurements of 64.
- With the Z300-VC10EV3, at an average number of measurements of 64.
  With the Z300-VC10EV3, at an average number of measurements of 512.
- 10. Value for measurement with 1 line (high speed) set in CCD Mode.
- 11. Value for measurement with the space between the Sensor and the workpiece (Z300-S5T/S10/S60: white alumina ceramic; Z300-S2T: quartz glass) secured with an aluminum jig.

Cont	roller: Z300-VC10V3					
Item		VISUAL mode	NON-VISUAL mode			
	Supply voltage	21.6 to 26.4 VDC (including ripple)				
	Current consumption	1 A max. (with 2 Sensors connected)				
	•	20 M $\Omega$ min. between all DC external terminals and GR terminal (100 VDC Megger, with internal surge absorber removed)				
	Insulation resistance					
ions		1000 VAC, 50/60 Hz between all DC external terminals and GR terminal				
	Dielectric strength	(with internal surge absorber removed)				
cat	Leakage current	10 mA max.				
cifi	Noise resistance	1500 Vp-p; Pulse width: 0.1 µs/ 1 µs; Rising edge: 1-ns p	pulse			
General specifications	Vibration resistance	10 to 150 Hz (double amplitude: 0.1 mm) for 8 min. each in X, Y, and Z directions				
	Shock resistance	$200 \text{ m/s}^2$ , 3 times each in 6 directions				
	Ambient temperature		Operating: 0 to +50 °C, Storage: -15 to +60 °C (with no icing or condensation)			
Ger	Ambient humidity	Operating and storage: 35 % to 85 % (with no condensation)				
	Ambient environment	No corrosive gases				
	Ground	Ground the Z300's ground terminal to less than 100 $\Omega$				
	Degree of protection	IEC60529 IP20 (in-panel)				
	Case material	Controller: ABS				
	Number of Sensors					
	that can be mounted	2	1			
	Number of scenes	16	1			
	Image memory	NG images: 20 scenes max.; Surrounding images: 4				
	function	scenes max.; Workpiece display images: 4 scenes max.				
	Processing method	Gray center of gravity, edge centering	Edge centering			
	Pre-image processing	Noise removal, smoothing	None			
		Average number of times (12 stages, 1 to 4096 times),	Average number of times			
	Averaging/filtering	HPF (high pass filter)	(SLOW: 64 times; FAST: 1 time)			
	Light intensity	Automatic (The light intensity tracking range can be	Automatic (The light intensity tracking range can			
	tracking function	specified.)	not be specified.)			
	tracking function	Fixed (Select from 32 stages.)	Fixed (Select either HIGH or LOW.)			
		Select from the following 8 types:				
	Applications	Surface displacement, spot displacement, maximum				
		height, groove/indentation, level difference, transparent				
		workpiece thickness, level difference (2 Sensors), or				
		thickness (2 Sensors).				
S	Region specification	Region specification of line beam and displacement direction is possible.				
specifications	Two region					
cat	measurement modes	Absolute coordinate mode and relative coordinate mode				
cifi	Hold functions	Sampling, peak, bottom, peak-to-peak, average, and length				
spe	Two Sensor	Simultaneous measurement and alternate				
	measurement modes	measurement				
anc	Measurement data	4 outputs per scene	1 output			
Performance		The following operations are possible for outputs 0 to 3:				
sto		K+A, K-A, K+(A+B), K+(A-B), and K-(A+B)				
Ъ	Equations	A and B: Specified measurement points				
		K: Freed constant				
		Judgement output (HIGH, PASS, LOW, ERROR)				
		→ RS-232C output				
		Terminal block output				
	Results output	Measurement value output (measurement value)	Analog output			
		→ RS-232C output				
		Terminal block output				
		Analog output				
		11 input points: TRIGGER, HOLD-RESET, LD-OFF,				
	Terminal block	ALL- <u>ZERO, ZERO</u> 0, ZERO1, RESET,				
		and DI 0 to DI 3	LD-OFF			
		21 output points: DO0 to DO20				
	Monitor interface	1 channel (for pin jack or overscan monitor)				
		The full scale for output can be divided into a maximum of	of 40000 gradations.			
	Analog output Besolution (See note )*0.25 mV (+5.V)					
	resolution	0.4 μA (4 to 20 μA)				
	Weight	Approx. 700 g (Controller only)				
	-	age number of times of 64 with an OMPON K2AS Linear Senser Cent				

Note: For measurement at an average number of times of 64 with an OMRON K3AS Linear Sensor Controller connected.

Monitor

Moni	tor Liquid Crystal Monitor	Video Monitor		
Item Mo	del F150-M05L	F150-M09		
Size	5.5 type	9 inches		
Туре	TFT color LCD	Monochrome CRT		
Resolution 320 × 240 dots		800TV or higher (center)		
Input signal	NTSC composite video (1.0 V / 75 Ω)			
Supply voltage	e 20.4 to 26.4 VDC	100 to 240 VAC (-15 %, +10 %)		
Current consumption	Approx. 700 mA	Approx. 200 mA		
Ambient temperature	Operating: 0 °C to 50 °C, Storage: -25 °C to 65 °C (with no icing or condensation)	Operating: -10 °C to 50 °C, Storage: -20 °C to 65 °C (with no icing or condensation)		
Ambient humidity	Operating/Storage: 35 % to 85 %RH (with no condensation)	Operating/Storage: 10 % to 90 %RH (with no condensation)		
Weight (Unit only)	Approx. 1 kg	Approx. 4.5 kg		
Accessories	Operation manual, 4 clamps	Instruction manual		

## **Laser Safety**

The Z300-S2T, Z300-Z5T and Z300-S10 Sensor Heads are Class 2 Laser Products according to EN60825-1 (IEC825-1) and Class II Laser Product according to FDA (21 CFR1040.10) (see note). The Z300-S60 Sensor Head is a Class 3B and Class IIIB Laser Product, respectively. The Z300 Series is meant to be built into final system equipment. Pay special attention to the following precautions for the safe use of the product:

Note: Europe: Class 2 and Class 3B of EN60825-1: 1994 = IEC815-1: 1993 U.S.A.: Class II and Class IIIB of FDA (21 CFR1040.10)

	Z300-S2T	Z300-S5T	Z300-S10	Z300-S60
Wavelength	650 nm	670 nm	658 nm	
Peak power	1 mW max.	15 mW max.		
Class	2	3B		
Maximum pulse duration	7 ms	17.5 ms		
Period	0.5 to 10 ms			0.5 to 25 ms

- Use this product as specified in the operation manual. Otherwise, you may be exposed to hazardous laser radiation.
- (2) The Z300 series radiates laser beams in the visible light range. Do not expose your eyes directly to the laser radiation. Ensure that the laser beam path is terminated during use. If a mirror or shiny surface is positioned in the laser beam path, ensure that the reflected beam path is also terminated.

If the Unit must be used without terminating the laser beam path, position the laser beam path so that it is not at eye level.

- (3) To avoid exposure to hazardous laser radiation, do not displace nor remove the protective housing during operation, maintenance, and any other servicing.
- (4) The user should return the product to OMRON for all repair and servicing.
- (5) As for countries other than those of Europe and the U.S.A., observe the regulations and standards specified by each country.

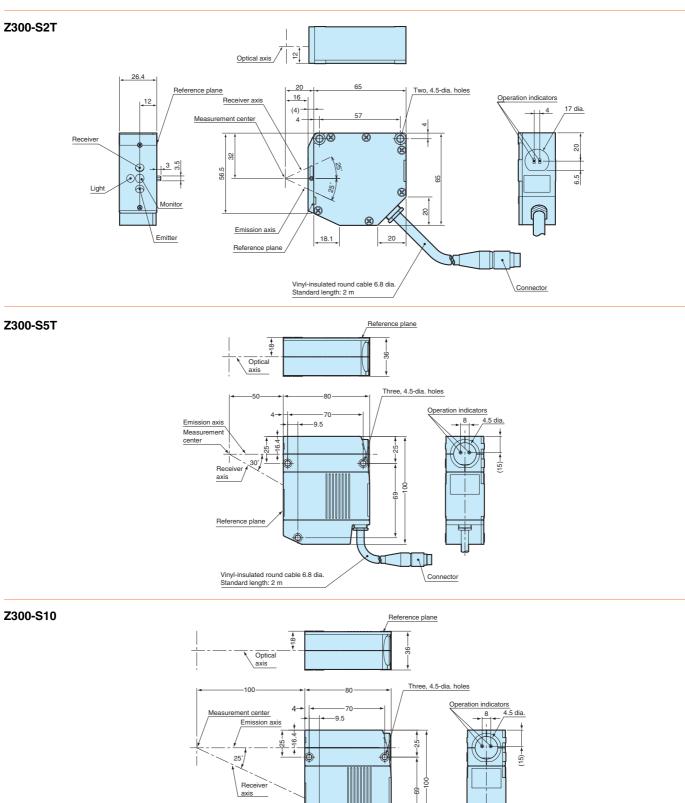
## **Precautions**

#### Warming up

After turning on the power, wait about 30 minutes before using the equipment. The circuits are not stable after turning on the power, and thus measured values tend to gradually drift.

# Dimensions (Unit: mm)

#### Sensor



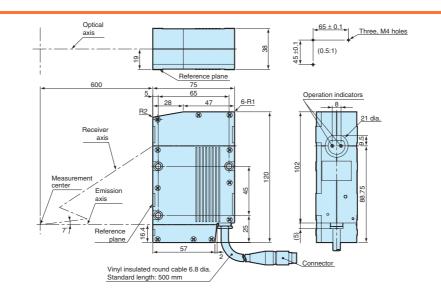
Reference plane

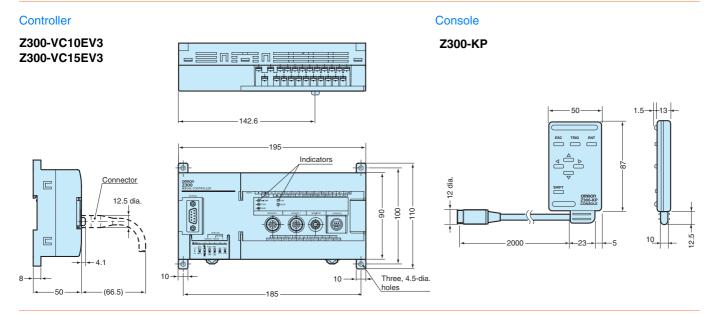
Vinyl-insulated round cable 6.8 dia. Standard length: 2 m П

M

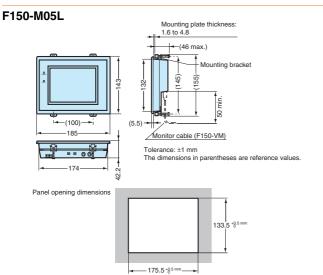
Connector

#### Z300-S60





#### LCD monitor



### Video monitor F150-M09

